7

Integration

7.1 TWO EXAMPLES

Up to now we have been concerned with extracting information about how a function changes from the function itself. Given knowledge about an object’s position, for example, we want to know the object’s speed. Given information about the height of a curve we want to know its slope. We now consider problems that are, whether obviously or not, the reverse of such problems.

EXAMPLE 7.1.1 An object moves in a straight line so that its speed at time \( t \) is given by \( v(t) = 3t \) in, say, cm/sec. If the object is at position 10 on the straight line when \( t = 0 \), where is the object at any time \( t \)?

There are two reasonable ways to approach this problem. If \( s(t) \) is the position of the object at time \( t \), we know that \( s'(t) = v(t) \). Because of our knowledge of derivatives, we know therefore that \( s(t) = \frac{3t^2}{2} + k \), and because \( s(0) = 10 \) we easily discover that \( k = 10 \), so \( s(t) = \frac{3t^2}{2} + 10 \). For example, at \( t = 1 \) the object is at position \( \frac{3(1)^2}{2} + 10 = \frac{15}{2} \). This is certainly the easiest way to deal with this problem. Not all similar problems are so easy, as we will see, the second approach to the problem is more difficult but also more general.

We start by considering how we might approximate a solution. We know that at \( t = 0 \) the object is at position 10. How might we approximate its position at, say, \( t = 1 \)? We know that the speed of the object at time \( t = 0 \) is 0; if its speed were constant then in the first second the object would not move and its position would still be 10 when \( t = 1 \). In fact, the object will not be too far from 10 at \( t = 1 \), but certainly we can do better. Let’s look at the times 0.1, 0.2, 0.3, … , 1.0, and try approximating the location of the object at each, by supposing that during each tenth of a second the object is going at a constant speed. Since the object initially has speed 0, we again suppose it maintains this speed, but only for a tenth of a second; during that time the object would not move. During the tenth of a second from \( t = 0.1 \) to \( t = 0.2 \), we suppose that the object is traveling at 0.3 cm/sec, namely, its actual speed at \( t = 0.1 \). In this case the object would travel \( 0.3(0.1) = 0.03 \) centimeters: 0.3 cm/sec times 0.1 seconds. Similarly, between \( t = 0.2 \) and \( t = 0.3 \) the object would travel \( 0.06(0.1) = 0.06 \) centimeters. Continuing, we get as an approximation that the object travels

\[
(0.0)(0.1) + (0.3)(0.1) + (0.6)(0.1) + \cdots + (2.7)(0.1) = 1.35
\]

centimeters, ending up at position 11.35. This is a better approximation than 10, certainly, but is still just an approximation. (We know in fact that the object ends up at position 11.5, because we’ve already done the problem using the first approach.) Presumably, we will get a better approximation if we divide the time into one hundred intervals of a hundredth of a second each, and repeat the process:

\[
(0.0)(0.01) + (0.03)(0.01) + (0.06)(0.01) + \cdots + (2.97)(0.01) = 1.495
\]

We thus approximate the position as 11.485. Since we know the exact answer, we can see that this is much closer, but if we did not already know the answer, we wouldn’t really know how close.

We can keep this up, but we’ll never really know the exact answer if we simply compute more and more examples. Let’s instead look at a “typical” approximation. Suppose we divide the time into \( n \) equal intervals, and imagine that on each of these the object travels at a constant speed. Over the first time interval we approximate the distance traveled as \( (0.0/1)(0/1) = 0 \), as before. During the second time interval, from \( t = 1/n \) to \( t = 2/n \), the object travels approximately \( 1/1)(n/1)n = 3/n^2 \) centimeters. During time interval \( n \), the object travels approximately \( 3/1)(1/n)(1/n) = 3 / n^2 \) centimeters, that is, its speed at time \( (i-1)/n \). But in \( 1/n \), times the length of time interval \( n = 1/n \), \( 1/n \), so

\[
\text{approximate distance traveled} \approx \sum_{i=1}^{n} \frac{3}{n^2}
\]

This simplifies the approximate distance traveled to

\[
\frac{3n^3 - n}{2} + \frac{3n^3 - n}{2} - \frac{3n^3 - 1}{2} = 3 \left( 1 - \frac{1}{n} \right).
\]

Now this is quite easy to understand: as \( n \) gets larger and larger this approximation gets closer and closer to \((3/2)(1-0)/3 = 3/2\), so that \(3/2\) is the exact distance traveled during one second, and the final position is \(11.5\).

So for \( t = 1 \), at least, this rather cumbersome approach gives the same answer as the first approach. But really there’s nothing special about \( t = 1 \); let’s just call it \( t \) instead. In this case the approximate distance traveled during time interval \( i \) is \( 3(i-1)/i(n)(i/n) = 3(i-1)/i^2 \), that is, speed \((i-1)/i(n)\) times time \( i/n \), and the total distance traveled is approximately

\[
\left(0 \frac{3}{n^2} + 3 \left(1 \frac{3}{n^2} \right) + 3 \left(2 \frac{3}{n^2} \right) + \cdots + 3 \left(n-1 \frac{3}{n^2} \right) \right)
\]

As before we can simplify this to

\[
\frac{3n^2}{n^2} + \left(0 + 1 + 2 + \cdots + (n-1) \right) = \frac{3n^2 - n}{2} - \frac{3}{2} \left( 1 - \frac{1}{n} \right).
\]

In the limit, as \( n \) gets larger, this gets closer and closer to \((3/2)2^2\), and the approximated position of the object gets closer and closer to \((3/2)2^2 = 10\), so the actual position is \((3/2)2^2 = 10\), exactly the answer given by the first approach to the problem.

EXAMPLE 7.1.2 Find the area under the curve \( y = 3x \) between \( x = 0 \) and any positive value \( x \). There is here no obvious analogue to the first approach in the previous example,

134 Chapter 7 Integration

but the second approach works fine. (Because the function \( y = 3x \) is so simple, there is another approach that works here, but it is even more limited in potential application than is approach number one.) How might we approximate the desired area? We know how to compute areas of rectangles, so we approximate the area by rectangles. Jumping straight to the general case, suppose we divide the interval between 0 and \( x \) into \( n \) equal subintervals, and use a rectangle above each subinterval to approximate the area under the curve. There are many ways we might do this, but let’s use the height of the curve at the left endpoint of the subinterval as the height of the rectangle, as in figure 7.1.1. The height of rectangle number \( i \) is then \( 3(i - 1)/x \), the width is \( x/n \), and the area is \( 3(i-1)(x^2/n^2) \). The total area of the rectangles is

\[
\left(0 \frac{3}{n^2} + 3 \left(1 \frac{3}{n^2} \right) + 3 \left(2 \frac{3}{n^2} \right) + \cdots + 3 \left(n-1 \frac{3}{n^2} \right) \right)
\]

By factoring out \( 3x^2/n^2 \) this simplifies to

\[
\frac{3x^2}{n^2} \left(0 + 1 + 2 + \cdots + (n-1) \right) = \frac{3x^2 - n}{2} - \frac{3}{2} \left( 1 - \frac{1}{n} \right)
\]

As \( n \) gets larger this gets closer and closer to \( 3x^2/2 \), which must therefore be the true area under the curve.

Figure 7.1.1 Approximating the area under \( y = 3x \) with rectangles. Drag the slider to change the number of rectangles.

What you will have noticed, of course, is that while the problem in the second example appears to be much different than the problem in the first example, and while the easy approach to problem one does not apply to apply to problem two, the “approximation” approach works in both, and moreover the calculations are identical. As we will see, there
are many, many problems that appear much different on the surface but that turn out to
be the same as those problems, in the sense that when we try to approximate solutions we
end up with mathematics that looks like the two examples, though of course the function
involved will not always be so simple.

Even better, we now see that while the second problem did not appear to be amenable
to approach one, it can in fact be solved in the same way. The reasoning is this: we know
that problem one can be solved easily by finding a function whose derivative is \( f \). We
also know that mathematically the two problems are the same, because both can be solved
by taking a limit of a sum, and the sums are identical. Therefore, we don’t really need to
calculate the limit of either sum because we know that we will get the same answer by
computing a function with the derivative \( f \) or, which is the same thing, \( 3x \).

It’s true that the first problem had the added complication of the "10", and we certainly
need to be able to deal with such minor variations, but that turns out to be quite simple.
The lesson then is this: whenever we can solve a problem by taking the limit of a sum of
a certain form, we can instead of computing the (often nasty) limit find a new function
with a certain derivative.

Exercises 7.1.
1. Suppose an object moves in a straight line so that its speed at time \( t \) is given by \( v(t) = 2t + 2 \),
and that at \( t = 1 \) the object is at position 5. Find the position of the object at \( t = 2 \).

2. Suppose an object moves in a straight line so that its speed at time \( t \) is given by \( v(t) = t^2 + 2 \),
and that at \( t = 0 \) the object is at position 5. Find the position of the object at \( t = 2 \).

3. By a method similar to that in example 7.1.2, find the area under \( y = 2x \) between \( x = 0 \)
and any positive value for \( x \).

4. By a method similar to that in example 7.1.2, find the area under \( y = 4x \) between \( x = 0 \) and
any positive value for \( x \).

5. By a method similar to that in example 7.1.2, find the area under \( y = 4x \) between \( x = 2 \) and
any positive value for \( x \) bigger than 2.

6. By a method similar to that in example 7.1.2, find the area under \( y = 4x \) between any two
positive values for \( x \), say \( a < b \).

7. Let \( f(x) = x^2 + 3x + 2 \). Approximate the area under the curve between \( x = 0 \) and \( x = 2 \)
using 4 rectangles and also using 8 rectangles.

7.2 The Fundamental Theorem of Calculus

Let’s recall the first example from the previous section. Suppose that the speed of the
object is \( 3t \) at time \( t \). How far does the object travel between time \( t = a \) and time \( t = b \)?
We are no longer assuming that we know where the object is at time \( t = 0 \) or at any other
time. It is certainly true that it is somewhere, so let’s suppose that at \( t = 0 \) the position is \( b \).
Then just as in the example, we know that the position of the object at any time is \( 3t^2/2 + k \).
This means that at time \( t = a \) the position is \( 3a^2/2 + k \) and at time \( t = b \) the position
is \( 3b^2/2 + k \). Therefore the change in position is \( 3b^2/2 + k - (3a^2/2 + k) = 3b^2/2 - 3a^2/2 \).
Notice that the \( k \) drops out, this means that it doesn’t matter that we don’t know \( k \).

It doesn’t even matter if we use the wrong \( k \), we get the correct answer. In other words, to
find the change in position between time \( a \) and time \( b \), we can use any antiderivative of the
speed function \( 3t \); it need not be the one antiderivative that actually gives the location of
the object.

What about the second approach to this problem, in the new form? We now want to
approximate the change in position between time \( a \) and time \( b \). We take the interval of
time between \( a \) and \( b \), divide it into \( n \) subintervals, and approximate the distance traveled
during each. The starting time of subinterval number \( i \) is now \( a + (i - 1)\Delta t/n \), where we
abbreviate \( a_{i-1} \) so that \( a_0 = a \), \( t_1 = a + (b - a)/n \), and so on. The speed of the object
is \( f(t) = 3t \), and each subinterval is \( (b - a)/n = \Delta t \) seconds long. The distance
traveled during subinterval number \( i \) is approximately \( f(t_i)\Delta t \), and the total change in
distance is approximately

\[
\int_a^b f(t) \, dt = \sum_{i=1}^{n-1} f(t_i) \Delta t + f(t_{n-1}) \Delta t.
\]

The exact change in position is the limit of this sum as \( n \) goes to infinity. We abbreviate this
sum using sigma notation:

\[
\sum_{i=1}^{n-1} f(t_i) \Delta t = \int_a^b f(t) \, dt + f(t_{n-1}) \Delta t.
\]

The notation on the left side of the equal sign uses a large capital sigma, a Greek letter,
and the left side is an abbreviation for the right side. The answer we seek is

\[
\lim_{n \to \infty} \sum_{i=1}^{n-1} f(t_i) \Delta t = \int_a^b f(t) \, dt.
\]

Since this must be the same as the answer we have already obtained, we know that

\[
\lim_{n \to \infty} \sum_{i=1}^{n-1} f(t_i) \Delta t = \frac{3b^2}{2} - \frac{3a^2}{2}.
\]

The significance of \( 3b^2/2 \), into which we substitute \( t = b \) and \( t = a \), is of course that it is
a function whose derivative is \( f(t) \). As we have discussed, by the time we know that we
want to compute

\[
\lim_{n \to \infty} \sum_{i=1}^{n-1} f(t_i) \Delta t,
\]
it no longer matters what \( f(t) \) stands for—it could be a speed, or the height of a curve,
or something else entirely. We know that the limit can be computed by finding any
function with derivative \( f(t) \), substituting \( a \) and \( b \), and subtracting. We summarize this in
a theorem. First, we introduce some new notation and terms. We
write

\[
\int_a^b f(t) \, dt = \lim_{n \to \infty} \sum_{i=1}^{n-1} f(t_i) \Delta t
\]

if the limit exists. That is, the left hand side means, or is an abbreviation for, the right
hand side. The symbol \( \int \) is called an integral sign, and the whole expression is read as
"the integral of \( f(t) \) from \( a \) to \( b \)." What we have learned is that this integral can be
computed by finding a function, say \( F(t) \), with the property that \( F'(t) = f(t) \), and then
computing \( F(b) - F(a) \). The function \( F(t) \) is called an antiderivative of \( f(t) \). Now the
theorem:

**THEOREM 7.2.1** Fundamental Theorem of Calculus

Suppose that \( f(x) \) is continuous on the interval \([a, b] \). If \( F(x) \) is any antiderivative of \( f(x) \), then

\[
\int_a^b f(x) \, dx = F(b) - F(a).
\]

Let’s rewrite this slightly:

\[
\int_a^b f(t) \, dt = F(b) - F(a).
\]

We’ve replaced the variable \( x \) by \( t \) and \( b \) by \( x \). These are just different names for quantities,
so the substitution doesn’t change the meaning. It does make it easier to think of the two
sides of the equation as functions. The expression

\[
\int_a^b f(t) \, dt
\]

is a function: plug in a value for \( x \) and get out some other value. The expression \( F(x) - F(a) \)
is of course also a function, and it has a nice property:

\[
\frac{d}{dx}(F(x) - F(a)) = F'(x) = f(x).
\]
Proof of Theorem 7.2.1. We know from theorem 7.2.2 that

\[ G(x) = \int_a^x f(t) \, dt \]

is an antiderivative of \( f(x) \), and therefore any antiderivative \( F(x) \) of \( f(x) \) is of the form

\[ F(x) = G(x) + k. \]

Then

\[ F(b) - F(a) = G(b) + k - (G(a) + k) = G(b) - G(a) = \int_a^b f(t) \, dt - \int_a^a f(t) \, dt. \]

It is not hard to see that \( \int_a^a f(t) \, dt = 0 \), so this means that

\[ F(b) - F(a) = \int_a^b f(t) \, dt, \]

which is exactly what theorem 7.2.1 says.

So the real job is to prove theorem 7.2.2. We will sketch the proof, using some facts that we do not prove. First, the following identity is true of integrals:

\[ \int_a^b f(t) \, dt = \int_a^c f(t) \, dt + \int_c^b f(t) \, dt. \]

This can be proved directly from the definition of the integral, that is, using the limits of sums. It is quite easy to see that it must be true by thinking of either of the two applications of integrals that we have seen. It turns out that the identity is true no matter what \( c \) is, but it is easiest to think about the meaning when \( a < c < b \).

First, if \( f(t) \) represents a speed, then we know that the three integrals represent the distance traveled between time \( a \) and time \( b \); the distance traveled between time \( a \) and time \( c \); and the distance traveled between time \( c \) and time \( b \). Clearly the sum of the latter two is equal to the first of these.

Second, if \( f(t) \) represents the height of a curve, the three integrals represent the area under the curve between \( a \) and \( b \); the area under the curve between \( a \) and \( c \); and the area under the curve between \( c \) and \( b \). Again it is clear from the geometry that the first is equal to the sum of the second and third.

7.2 The Fundamental Theorem of Calculus

Now we know that to solve certain kinds of problems, those that lead to a sum of a certain form, we “merely” find an antiderivative and substitute two values and subtract. Unfortunately, finding antiderivatives can be quite difficult. While there are a small number of rules that allow us to compute the derivative of any common function, there are no such rules for antiderivatives. There are some techniques that frequently prove useful, but we will never be able to reduce the problem to a completely mechanical process.

Because of the close relationship between an integral and an antiderivative, the integral sign is also used to mean “antiderivative.” You can tell which is intended by whether the limits of integration are included:

\[ \int_a^b x^2 \, dx \]

is an ordinary integral, also called a definite integral, because it has a definite value, namely

\[ \int_a^b x^2 \, dx = \frac{b^3}{3} - \frac{a^3}{3} + \frac{7}{3}. \]

We use

\[ \int_a^b x^2 \, dx \]

to denote the antiderivative of \( x^2 \), also called an indefinite integral. So this is evaluated as

\[ \int x^2 \, dx = \frac{x^3}{3} + C. \]

It is customary to include the constant \( C \) to indicate that there are really an infinite number of antiderivatives. We do not need this to compute definite integrals, but in other circumstances we will need to remember that the \( C \) is there, so it is best to get into the habit of writing the \( C \). When we compute a definite integral, we first find an antiderivative and then substitute. It is convenient to first display the antiderivative and then do the substitution; we need a notation indicating that the substitution is yet to be done. A typical solution would look like this:

\[ \int_2^3 x^2 \, dx = \frac{x^3}{3} \bigg|_2^3 = \frac{27}{3} - \frac{8}{3} = \frac{19}{3}. \]

The vertical line with subscript and superscript is used to indicate the operation “substitute and subtract” that is needed to finish the evaluation.

144 Chapter 7 Integration

Exercises 7.2.

1. \( \int \sqrt{3} \, dx \)
2. \( \int 3x^3 + 1 \, dx \)
3. \( \int \sqrt{3} \, dx \)
4. \( \int 2x^2 \, dx \)
5. \( \int (3x + 1)^2 \, dx \)
6. \( \int (x - 6)^2 \, dx \)
7. \( \int x^{3/2} \, dx \)
8. \( \int 2x^{1/2} \, dx \)
9. \( \int 2t - 4 \, dt \)

Compute the values of the integrals:
10. \( \int_2^3 3x + 3 \, dx \)
11. \( \int_1^2 \sin t \, dt \)
12. \( \int_2^3 x^2 \, dx \)
13. \( \int_1^2 x^3 \, dx \)
14. Find the derivative of \( G(x) = \int_1^x 3t^2 - 3t \, dt \)
15. Find the derivative of \( G(x) = \int_2^x 3t^2 - 3t \, dt \)
16. Find the derivative of \( G(x) = \int_0^x \tan(t^2) \, dt \)
17. Find the derivative of \( G(x) = \int_1^x \tan(t^2) \, dt \)

7.3 Some Properties of Integrals

Suppose an object moves so that its speed, or more properly velocity, is given by \( v(t) = -t^2 + 5t \), as shown in figure 7.3.1. Let’s examine the motion of this object carefully.

We know that the velocity is the derivative of position, so position is given by \( s(t) = -t^3/3 + 5t^2/2 + C \). Let’s suppose that at time \( t = 0 \) the object is at position 0, so \( s(0) = -0^3/3 + 5(0)^2/2 + C = 0 \), so \( C = 0 \).

Between \( t = 0 \) and \( t = 5 \) the velocity is positive, so the object moves away from the starting point, until it is a bit past position 20. Then the velocity becomes negative and the object moves back toward its starting point. The position of the object at \( t = 5 \) is exactly \( s(5) = 125/6 \), and at \( t = 6 \) it is \( s(6) = 18 \). The total distance traveled by the object is therefore \( 125/6 + (125/6 - 18) = 77/6 + 237/6 = 214/6 = 35.67 \). As we have seen, we can also compute distance traveled with an integral; let’s try it.

\[ \int_0^6 v(t) \, dt = \int_0^5 -t^2 + 5t \, dt = \left[ -\frac{t^3}{3} + \frac{5t^2}{2} \right]_0^5 = \frac{125}{3} - \frac{50}{2} = 18. \]

What went wrong? Well, nothing really, except that it’s not really true after all that “we can also compute distance traveled with an integral.” Instead, as you might guess from this
7.3 Some Properties of Integrals

The values \( v(t) \) are positive but \( \Delta t \) is negative, and we get a negative result:

\[
\int_0^5 v(t) \, dt = -\frac{25}{3} - \frac{25}{3} = -\frac{50}{3}
\]

Finally we note one simple property of integrals:

\[
\int_a^b f(x) \, dx + g(x) \, dx = \int_a^b f(x) \, dx + \int_{g(x)}^b g(x) \, dx.
\]

This is easy to understand once you recall that \((F(x) + G(x))' = F'(x) + G'(x)\). Hence, if \(F'(x) = f(x)\) and \(G'(x) = g(x)\), then

\[
\int_a^b f(x) + g(x) \, dx = \int_a^b F(x) + G(x) \, dx
\]

is negative, so all terms are positive again. On the other hand, in

\[
\int_0^6 v(t) \, dt = \sum_{i=0}^{i=6} v(t_i) \Delta t.
\]

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\int_0^6 v(t) \, dt = \sum_{i=0}^{i=6} v(t_i) \Delta t.
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\int_0^5 v(t) \, dt = -\frac{25}{3} - \frac{25}{3} = -\frac{50}{3}
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Finally we note one simple property of integrals:

\[
\int_a^b f(x) \, dx + g(x) \, dx = \int_a^b f(x) \, dx + \int_{g(x)}^b g(x) \, dx.
\]

This is easy to understand once you recall that \((F(x) + G(x))' = F'(x) + G'(x)\). Hence, if \(F'(x) = f(x)\) and \(G'(x) = g(x)\), then

\[
\int_a^b f(x) + g(x) \, dx = \int_a^b F(x) + G(x) \, dx
\]

is negative, so all terms are positive again. On the other hand, in

\[
\int_0^6 v(t) \, dt = \sum_{i=0}^{i=6} v(t_i) \Delta t.
\]
\[
\int \sin x \, dx = -\cos x + C \\
\int \cos x \, dx = \sin x + C \\
\int \sec^2 x \, dx = \tan x + C \\
\int \csc x \cot x \, dx = \csc x + C \\
\int \frac{1}{x+2} \, dx = \ln|x+2| + C \\
\int \frac{1}{\sqrt{1-x^2}} \, dx = \arcsin x + C \\
\]

This is not a “simple” derivative, but a little thought reveals that it must have come from an application of the chain rule. Multiplied on the “outside” is 2x, which is the derivative of the “inside” function x^2. Checking:

\[
\frac{d}{dx}\sin(x^2) = \cos(x^2) \cdot 2x,
\]

so

\[
2x \cos(x^2) \, dx = \sin(x^2) + C.
\]

Even when the chain rule has “produced” a certain derivative, it is not always easy to see. Consider this problem:

\[
\int x^3 \sqrt{1-x^3} \, dx.
\]

There are two factors in this expression, x^3 and \sqrt{1-x^3}, but it is not apparent that the chain rule is involved. Some clever rearrangement reveals that it is:

\[
\int x^3 \sqrt{1-x^3} \, dx = \int (-2x) \left(1 - \left(1 - x^3\right)^{1/2}\right) \, dx.
\]

This looks messy, but do now have something that looks like the result of the chain rule: the function 1 - x^3 has been substituted into \(-1/2(1-x)\sqrt{1-x^2}\), and the derivative of 1 - x^2, -2x, multiplied on the outside. If we can find a function F(x) whose derivative is \(-1/2(1-x)\sqrt{1-x^2}\), we’ll be done, since then

\[
\frac{d}{dx} F(x^3) = -2x F'(1-x^2) = \left(-2x\right) \left(\frac{1}{2} \left(1 - (1-x^2)\right)\sqrt{1-x^2}\right) = x^3 \sqrt{1-x^2},
\]

But this isn’t hard:

\[
\int \frac{1}{2}(1-x)\sqrt{1-x^2} \, dx = \int \frac{1}{2} x^{3/2} - x^{3/2} \, dx = \left[\frac{1}{5} x^{5/2} - \frac{3}{2} x^{3/2}\right] = \left(\frac{1}{5} x^{5/2} - \frac{3}{2} x^{3/2}\right) + C
\]

So finally we have

\[
\int x^3 \sqrt{1-x^3} \, dx = \frac{1}{5} x^{5/2} - \frac{3}{2} x^{3/2} + C.
\]

So we succeeded, but it required a clever first step, rewriting the original function so that it looked like the result of using the chain rule. Fortunately, there is a technique that makes such problems simpler, without requiring cleverness to rewrite a function in just the right way. It does sometimes not work, or may require more than one attempt, but the idea is simple: guess at the most likely candidate for the “inside function”, then do some algebra to see what this requires the result of the function to look like.

One frequently good guess is any complicated expression inside a square root, so we start by trying u = 1 - x^2, using a new variable, u, for convenience in the manipulations that follow. Now we know that the chain rule will multiply by the derivative of this inner function:

\[
\frac{du}{dx} = -2x,
\]

so we need to rewrite the original function to include this:

\[
\int x^3 \sqrt{1-x^3} \, dx = \int x^3 \sqrt{1-u} \, \frac{du}{-2x} = -\frac{1}{2} \int x^3 \sqrt{1-u} \, du.
\]

Recall that one benefit of the Leibniz notation is that it often turns out that what looks like ordinary arithmetic gives the correct answer, even if something more complicated is going on. For example, in Leibniz notation the chain rule is

\[
\frac{dy}{dx} = \frac{du}{dx} \frac{dy}{du}.
\]

The same is true of our current expression:

\[
\int x^3 \sqrt{1-x^3} \, dx = \int x^3 \sqrt{1-u} \, \frac{du}{-2x}.
\]

Now we’ve almost there: since u = 1 - x^2, x^2 = 1 - u and the integral is

\[
\int \frac{1}{2}(1-u)\sqrt{1-u} \, du.
\]

It’s no coincidence that this is exactly the integral we computed in (7.4.1). We have simply renamed the variable u to make the calculations less confusing. Just as before:

\[
\int \frac{1}{2}(1-u)\sqrt{1-u} \, du = \left[\frac{1}{5} u^{5/2} - \frac{3}{2} u^{3/2}\right] + C.
\]

Then since u = 1 - x^2:

\[
\int x^3 \sqrt{1-x^3} \, dx = \left[\frac{1}{5} (1-x^2)^{5/2} - \frac{3}{2} (1-x^2)^{3/2}\right] + C.
\]

To summarize: if we suspect that a given function is the derivative of another via the chain rule, we let u denote a likely candidate for the inner function, then translate the given function so that it is written entirely in terms of u, with no x remaining in the expression. If we can integrate this new function of u, then the antiderivative of the original function is obtained by replacing u by the equivalent expression in x.

Even in simple cases you may prefer to use this mechanical procedure, since it often helps to avoid silly mistakes. For example, consider again this simple problem:

\[
\int 2x \cos(x^2) \, dx.
\]

Let u = x^2, then \(du/dx = 2x\) or \(du = 2x \, dx\). Since we have exactly 2x \, dx in the original integral, we can replace it by du:

\[
\int 2x \cos(x^2) \, dx = \int \cos u \, du = \sin u + C = \sin(x^2) + C.
\]

This is not the only way to do the algebra, and typically there are many paths to the correct answer. Another possibility, for example, is: Since \(du/dx = 2x\), \(dx = du/2x\), and

\[
7.4 \text{ Substitution}
\]

...
to substitute \( x^2 \) back in for \( u \), thus getting the incorrect answer \( -\frac{1}{2} \cos(4) + \frac{1}{2} \cos(2) \). A somewhat clumsy, but acceptable, alternative is something like this:

\[
\int \frac{1}{2} \sin (x^2) \, dx = \int \frac{1}{2} \sin u \, du = -\frac{1}{2} \cos(u) \bigg|_{u=2}^{u=4} = \frac{1}{2} \cos(2) - \frac{1}{2} \cos(4)
\]

**Example 7.4.4** Evaluate \( \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \cos(\pi t) \sin^2(\pi t) \, dt \). Let \( u = \sin(\pi t) \) so \( du = \pi \cos(\pi t) \, dt \) or \( \frac{du}{\pi} = \cos(\pi t) \, dt \). We change the limits to \( \sin(\pi/4) = \sqrt{2}/2 \) and \( \sin(\pi/2) = 1 \). Then

\[
\int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \cos(\pi t) \sin^2(\pi t) \, dt = \int_{\sqrt{2}/2}^{1} \frac{1}{2} \, du = \frac{1}{2} \left( \frac{1}{\pi} - \sqrt{2} \right)
\]

Exercises 7.4.

Find the antiderivatives or evaluate the definite integral in each problem.

1. \( \int (1 - t)^3 \, dt \) \( \Rightarrow \) 2. \( \int (t^2 + 1)^3 \, dt \) \( \Rightarrow \)
3. \( \int x^3 + 1 \, dx \) \( \Rightarrow \) 4. \( \int \frac{1}{\sqrt{x - 1}} \, dx \) \( \Rightarrow \)
5. \( \int \sin^2 x \, dx \) \( \Rightarrow \) 6. \( \int x \sqrt{x^2 - 1} \, dx \) \( \Rightarrow \)
7. \( \int \sqrt{x^3 + 1} \, dx \) \( \Rightarrow \) 8. \( \int \cos(\pi t) \cos(\sin(\pi t)) \, dt \) \( \Rightarrow \)
9. \( \int \sec x \, dx \) \( \Rightarrow \) 10. \( \int \tan x \, dx \) \( \Rightarrow \)
11. \( \int \sin^2(2x) \, dx \) \( \Rightarrow \) 12. \( \int \sec^2 x \tan x \, dx \) \( \Rightarrow \)
13. \( \int \sin^2 x \tan x \, dx \) \( \Rightarrow \) 14. \( \int \sin(\tan x) \, dx \) \( \Rightarrow \)
15. \( \int \frac{1}{\cos x} \, dx \) \( \Rightarrow \) 16. \( \int (\cos^2 x - \sin^2 x) \, dx \) \( \Rightarrow \)
17. \( \int \frac{6x}{(x^2 - 1)^2} \, dx \) \( \Rightarrow \) 18. \( \int e^x (e^x - 2)^2 \, dx \) \( \Rightarrow \)
19. \( \int \sin^2 x \, dx \) \( \Rightarrow \) 20. \( \int f(x) f'(x) \, dx \) \( \Rightarrow \)